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T. WINIARSKA

QUASILINEAR EVOLUTION EQUATIONS WITH OPERATORS DEPENDENT ON t

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The purpose of this paper is to present some theorems on existence and uniqueness of solutions for some semilinear Cauchy problems of second order with operators $A(t)$ not densely defined in a given Banach space X . To this end, we begin with reduction of our problem to a problem in which the operators have the same (independent of t) domain D .

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Целью этой работы является представление некоторых теорем о существовании и единственности решений некоторых полулинейных задач Коши второго порядка с операторами $A(t)$, не плотно определенными в заданном банаховом пространстве X . Для этого мы начинаем с редукции нашей задачи к задаче, в которой операторы имеют одну и ту же (независимую от t) область D .

1. Introduction. Our main objective is to investigate the abstract semilinear second order initial value problem

$$\begin{cases} \frac{d^2 u}{dt^2} = A(t)u + f\left(t, u, \frac{du}{dt}\right), & t \in (0, T], \\ u(0) = u_0, \quad \frac{du}{dt}(0) = u_1, & u_0, u_1 \in X \end{cases} \quad (1)$$

where $(X, \|\cdot\|)$ is a Banach space, u a mapping from \mathbb{R} to X , f a nonlinear mapping from $[0, T] \times X \times X$ into X and $\{A(t)\}$, $t \in [0, T]$ a family of linear closed operators

$$A(t): X \supset D_t \longrightarrow X$$

with domains $D_t \subset X$ depending on t unnecessarily dense in X .

Most of the results concerning problem (1) have been obtained under the assumption that the operators $\{A(t)\}$, $t \in [0, T]$, of a given family have domains independent of t (see e. g. [4, 5, 8]).

The case of densely defined operators $A(t)$ with domains dependent on t has been considered in [11].

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The main our goal is to present a result on existence and uniqueness of the mild solution for problem (1). To this end, we use some extrapolation spaces associated to the family $\{A(t)\}$, $t \in [0, T]$, in order to reduce problem (1) to a second order initial value problem with operators densely defined.

2. Preliminaries. We make the following assumptions on the family $\{A(t)\}$, $t \in [0, T]$.

- (Z₁) There exists a closed subspace $Y \subset X$ such that $Y = \bar{D}_t$ for each $t \in [0, T]$ and $Y \neq X$.
- (Z₂) For each $t \in [0, T]$ the resolvent set $\varrho(A(t)) = \varrho(A)$ of $A(t)$ is independent of $t \in [0, T]$ and $[0, \infty) \subset \varrho(A)$.
- (Z₃) The family $A(t)$, $t \in [0, T]$, is stable in the sense that there exists a real number $M \geq 1$ such that

$$\|(\lambda - A(t_k))^{-1}(\lambda - A(t_{k-1}))^{-1} \dots (\lambda - A(t_1))^{-1}\| \leq M\lambda^{-k} \quad (2)$$

and

$$\|(\lambda - A(t_1))^{-1}(\lambda - A(t_2))^{-1} \dots (\lambda - A(t_k))^{-1}\| \leq M\lambda^{-k}, \quad (3)$$

for $\lambda > 0$ and every finite sequence $0 \leq t_1 \leq t_2 \leq \dots \leq t_k \leq T$, $k \in \mathbb{N}$.

From the assumption (Z₃) for $k = 1$ it follows that

$$\|(\lambda - A(t))^{-1}\| \leq \frac{M}{\lambda} \quad \text{for } \lambda > 0, \quad t \in [0, T]. \quad (4)$$

It follows from (4) that it is possible to define for each $t \in [0, T]$ the operator

$$B(t)x = [A(t)]^{\frac{1}{2}}x := \frac{i}{\pi} \int_0^\infty \lambda^{-\frac{1}{2}} R(\lambda, A(t))(-A(t))x d\lambda,$$

where $x \in D_t$ (cf. [6]).

- (Z₄) For each $t \in [0, T]$, $\lambda > 0$ and $n \in \mathbb{N}$

$$\left\| \frac{d^n}{d\lambda^n} (\lambda(\lambda^2 - A(t))^{-1}) \right\| \leq \frac{Mn!}{\lambda^{n+1}},$$

and

$$\left\| \frac{d^n}{d\lambda^n} (B(t)(\lambda^2 - A(t))^{-1}) \right\| \leq \frac{Mn!}{\lambda^{n+1}},$$

where $M \geq 1$ is from (2) and (3).

- (Z₅) The mapping

$$[0, T] \ni t \longrightarrow R(\lambda, A(t))x \quad \text{is of class } C^1 \text{ for } x \in X.$$

- (Z₆) For each $t, s \in [0, T]$ the operator $A^{-1}(t)A(s)$ is closable and the mapping

$$[0, T] \ni t \longrightarrow \overline{A^{-1}(t)A(s)}$$

is continuous in $t = s$, i.e.

$$\lim_{t \rightarrow s} \|\overline{A^{-1}(t)A(s)} - I\| = 0$$

3. Existence and uniqueness of solution of problem (1). Following [11] we shall use some extrapolation spaces in order to reduce problem (1) to a similar problem with an operator $\hat{A}_0(t)$ densely defined in an extrapolation space \hat{X}_0 .

To this purpose we define for each $t \in [0, T]$ the operator $A_0(t)$,

$$A_0(t) := A(t)|_{D_t^0}, \quad D_t^0 := \{x \in D_t : A(t)x \in Y\},$$

i.e. $A_0(t)$ is the part of $A(t)$ in Y . By the definition of $A_0(t)$ we see that the operator $A_0(t): Y \supset D_t^0 \rightarrow Y$ is densely defined. In the space Y , for each $t \in [0, T]$, we define a weaker norm

$$|x|_t^{A_0} := \|R(0, A_0(t))x\|, \quad \text{for } x \in Y, t \in [0, T]$$

From (Z_6) it follows that for each $t \in [0, T]$ the norms $|\cdot|_t^{A_0}$ defined by (5) are equivalent (cf. [12]). Taking in the space Y the norm

$$|x|_0^{A_0} := \|R(0, A_0(0))x\| = \|A_0^{-1}(0)x\|, \quad \text{for } x \in Y \quad (5)$$

we denote by \hat{Y}^{A_0} the space which is the completion of the space Y with norm (5) to a Banach space. Since the operator

$$A_0(t): Y \supset D_t^0 \longrightarrow \hat{Y}^{A_0}$$

is bounded for each $t \in [0, T]$, we can extend it to the closure of its domain, i.e. to $\bar{D}_t^0 = Y$. Then we define

$$\hat{A}_0(t): \hat{Y}^{A_0} \supset Y \longrightarrow \hat{Y}^{A_0} \quad \text{for } t \in [0, T]$$

to be the extension of $A_0(t)$. In this way we get a family of linear densely defined operators $\{\hat{A}_0(t)\}$, $t \in [0, T]$, for which $D(\hat{A}_0(t)) = Y$ for $t \in [0, T]$, where Y is dense in \hat{Y}^{A_0} .

Our main objective of this paper is to consider problem (1) in the case when f is the mapping

$$f: [0, T] \times X \times X \longrightarrow X.$$

To the purpose we define \hat{X}_0^A as the completion of the space X with the norm

$$|x|_0^A = \|R(0, A(0))x\|, \quad x \in X$$

to a Banach space. By virtue of ([7], Th. 3.1.10) we may identify \hat{Y}^{A_0} with \hat{X}_0^A and $\hat{A}_0(t)$ with $\hat{A}(t)$, where all of the mappings

$$\hat{A}(t): \hat{X}_0^A \supset Y \longrightarrow \hat{X}_0^A, \quad t \in [0, T]$$

are defined on the same subspace Y which is dense in \hat{X}_0^A .

From now on we will consider the problem

$$\begin{cases} \frac{d^2 u}{dt^2} = \hat{A}(t)u + f(t, u, u') \\ u(0) = u_0 \in X \\ u'(0) = u_1 \in X. \end{cases} \quad (6)$$

Under assumptions (Z_1) – (Z_6) we get that the family $\{\hat{A}(t)\}$, $t \in [0, T]$, has the following properties:

- 1⁰. $D(\hat{A}(t)) = Y$, for each $t \in [0, T]$.
 2⁰. $D(\hat{A}(t))$ is dense in \hat{X}_0^A .
 3⁰. $\hat{A}(t)x = \hat{B}^2(t)x$, for each $t \in [0, T]$ and $x \in Y$, where

$$\hat{B}(t)x = \frac{i}{\pi} \int_0^\infty \lambda^{-\frac{1}{2}} R(\lambda, \hat{A}(t)) (-\hat{A}(t))x d\lambda \quad \text{for } x \in Y. \quad (7)$$

The operator $\hat{B}(t)$ may not be closed as an operator defined on \hat{X}_0^A , but it is closable because

$$\hat{B}^{-1}(t) = \frac{1}{\pi i} \int_0^\infty \lambda^{-\frac{1}{2}} R(\lambda, \hat{A}(t)) d\lambda$$

is bounded in \hat{X}_0^A .

In the sequel the closure of operator (7), i.e. the operator

$$\hat{B}(t): \hat{X}_0^A \supset D(\hat{B}(t)) \longrightarrow \hat{X}_0^A$$

will be denoted by the same symbol $\hat{B}(t)$.

Lemma 1. *Under assumptions (Z_1) – (Z_6) the family of operators*

$$\hat{B}(t)\hat{B}^{-1}(0): \hat{X}_0^A \longrightarrow \hat{X}_0^A$$

is uniformly bounded, i.e. there exists a constant $K \geq 0$ such that

$$|\hat{B}(t)\hat{B}^{-1}(0)x|_0^A \leq K|x|_0^A \quad \text{for } x \in \hat{X}_0^A, \quad t \in [0, T].$$

Proof. For $x \in (Y, |\cdot|_0^A) \subset \hat{X}_0^A$ we have

$$\begin{aligned} |\hat{B}(t)\hat{B}^{-1}(0)x|_0^A &= \|A_0^{-1}(0)\hat{B}(t)\hat{B}^{-1}(0)x\| \leq \\ &\leq \|A_0^{-1}(0)A_0(t)\| \|A_0^{-1}(t)\hat{B}(t)\hat{B}^{-1}(0)x\|. \end{aligned}$$

By (Z_6) , we have

$$\begin{aligned} |\hat{B}(t)\hat{B}^{-1}(0)x|_0^A &\leq C\|A_0^{-1}(t)\hat{B}(t)\hat{B}^{-1}(0)x\| = C\|A_0^{-1}(t)B(t)B^{-1}(0)x\| = \\ &= C\|B^{-1}(t)B^{-1}(0)x\| = C\|B^{-1}(t)B^{-1}(0)A_0(0)A_0^{-1}(0)x\| \leq \\ &\leq C\|B^{-1}(t)B^{-1}(0)A_0(0)\| |x|_0^A = C\|B^{-1}(t)B(0)\| |x|_0^A, \end{aligned}$$

where $C = \sup\{\|A_0^{-1}(t)A_0(t)\| : t \in [0, T]\}$. By virtue of ([11], Lemma 2), there exists $C_0 > 0$ such that

$$\|B^{-1}(t)B(0)\| \leq C_0 \quad \text{for } t \in [0, T]$$

which ends the proof (with $K = CC_0$). □

Lemma 2. *Under assumptions (Z_1) – (Z_6) the norms*

$$|||x|||_t := |\hat{B}(t)x|_0^A \quad \text{for } x \in Y$$

corresponding to $t \in [0, T]$ are equivalent.

Proof. Let $x \in (Y, |\cdot|_0^A)$ be arbitrary. By Lemma 1, $|\hat{B}(t)\hat{B}^{-1}(0)|_0^A \leq K$, for $t \in [0, T]$. Thus

$$|||x|||_t = |\hat{B}(t)x|_0^A = |\hat{B}(t)\hat{B}^{-1}(0)\hat{B}(0)x|_0^A \leq K|\hat{B}(0)x|_0^A = K|||x|||_0,$$

Similarly we get

$$|||x|||_0 = |\hat{B}(0)x|_0^A \leq L|\hat{B}(t)x|_0^A = L|||x|||_t,$$

where $L = \sup\{|\hat{B}(0)\hat{B}^{-1}(t)|_0^A : t \in [0, T]\}$. \square

Lemma 3. *Under the assumptions of Lemma 2 the family $\{\hat{B}(t)\}$, $t \in [0, T]$, has a constant domain, i.e. $D(\hat{B}(t)) = D(\hat{B}(0))$ for each $t \in [0, T]$.*

Proof. Let $x \in D(\hat{B}(0))$ and let $\{x_n\} \subset Y$ be such that $x_n \rightarrow x$ and $\hat{B}(0)x_n \rightarrow \hat{B}(0)x$ in \hat{X}_0^A . Since, for each $t \in [0, T]$, $Y \subset D(\hat{B}(t))$,

$$|\hat{B}(t)x_p - \hat{B}(t)x_q|_0^A = |\hat{B}(t)(x_p - x_q)|_0^A \leq M|\hat{B}(0)(x_p - x_q)|_0^A \rightarrow 0$$

when $p, q \rightarrow \infty$. This means that $\{\hat{B}(t)x_n\}$ satisfies the Cauchy condition. This implies the convergence of $\{\hat{B}(t)x_n\}$ in \hat{X}_0^A . Let $y \in \hat{X}_0^A$ be a limit of $\{\hat{B}(t)x_n\}$. Hence we have

$$x_n \xrightarrow{n \rightarrow \infty} x \quad \text{and} \quad \hat{B}(t)x_n \rightarrow y \quad \text{when } n \rightarrow \infty \quad (8)$$

From (8) and closeness of the operator $\hat{B}(t)$ it follows that $x \in D(\hat{B}(t))$ and $\hat{B}(t)x = y$. Thus $D(\hat{B}(0)) \subset D(\hat{B}(t))$, for each $t \in [0, T]$. Analogously we obtain the inverse inclusion, i.e. $D(\hat{B}(t)) \subset D(\hat{B}(0))$ for each $t \in [0, T]$.

We denote

$$D_0^B := D(\hat{B}(0)) = D(\hat{B}(t)), \quad t \in (0, T].$$

Since $Y \subset D_0^B$, D_0^B is a dense subspace of \hat{X}_0^A . We denote by $[D_0^B]$ the space D_0^B equipped with the graph norm of the operator $\hat{B}(0)$, i.e.

$$|x| := |x|_0^A + |\hat{B}(0)x|_0^A. \quad (9)$$

The space $[D_0^B]$ may be defined in another way. Since $0 \in \varrho(\hat{B}(t))$, for each $t \in [0, T]$, the norms $|x|_0^A + |\hat{B}(0)x|_0^A$ and $|\hat{B}(0)x|_0^A$ are equivalent for each $x \in D_0^B$. On the other hand we have

$$|\hat{B}(0)x|_0^A = \|R(0, \hat{A}(0))\hat{B}(0)x\| = \|\hat{A}^{-1}(0)\hat{B}(0)x\| = \|\hat{B}^{-1}(0)x\| = \|R(0, \hat{B}(0))x\|.$$

Denoting

$$|x|_0^B := \|R(0, \hat{B}(0))x\| \quad \text{for } x \in D_0^B, \quad (10)$$

we see that norms (9) and (10) are equivalent. From this we get

$$[D_0^B] = \hat{Y}^B,$$

where \hat{Y}^B is the space which is the completion of the space Y with norm (10) to a Banach space.

Using the extrapolation space \hat{X}_0^A and \hat{Y}^B we are able to reduce Cauchy problem (6) to the following first order problem in the space $\hat{Y}^B \times \hat{X}_0^A$:

$$\begin{cases} \frac{d\mathcal{U}}{dt} = \hat{\mathcal{A}}(t)\mathcal{U} + F(t, \mathcal{U}), \\ \mathcal{U}(0) = \mathcal{U}_0, \end{cases} \quad (11)$$

where

$$\begin{aligned} \mathcal{U} &= \begin{bmatrix} u \\ v \end{bmatrix}, \quad \hat{\mathcal{A}}(t) = \begin{bmatrix} 0 & I \\ \hat{A}(t) & 0 \end{bmatrix}, \quad F(t, \mathcal{U}) = \begin{bmatrix} 0 \\ f(t, u, v) \end{bmatrix}, \\ \mathcal{U}_0 &= \begin{bmatrix} u_0 \\ u_1 \end{bmatrix}, \quad v = u', \quad D(\hat{\mathcal{A}}(t)) = Y \times D_0^B. \end{aligned}$$

□

Theorem 1. Under assumptions (Z_1) – (Z_6) if

$$f: [0, T] \times X \times X \ni (t, x, y) \longrightarrow f(t, x, y) \in \hat{X}_0^A \quad \text{is of class } C^1$$

and

$$\|f(t, x_1, y_1) - f(t, x_2, y_2)\| \leq L(|x_1 - x_2|_0^B + |y_1 - y_2|_0^A), \quad (12)$$

$(u_0, v_0) \in D(\hat{\mathcal{A}}(t))$, then problem (11) has a unique classical solution $\mathcal{U} \in C^1([0, T], \hat{Y}^B \times \hat{X}_0^A)$, which is the unique solution of the integral equation

$$\mathcal{U}(t) = \mathcal{V}(t, 0)\mathcal{U}_0 + \int_0^t \mathcal{V}(t, s)F(s, \mathcal{U}(s))ds,$$

where $\mathcal{V}(t, s)$, $t, s \in [0, T]$ is the fundamental solution of problem (11).

Proof. From (Z_3) by ([11], Th. 5] it follows that the family $\{\hat{A}(t)\}$, $t \in [0, T]$, satisfies the following inequalities in the space \hat{X}_0^A :

$$\|(\lambda - \hat{A}(t_k))^{-1}(\lambda - \hat{A}(t_{k-1}))^{-1} \dots (\lambda - \hat{A}(t_1))^{-1}\| \leq \frac{\bar{M}}{\lambda^k}$$

and

$$\|(\lambda - \hat{A}(t_1))^{-1}(\lambda - \hat{A}(t_2))^{-1} \dots (\lambda - \hat{A}(t_k))^{-1}\| \leq \frac{\bar{M}}{\lambda^k}$$

for $\lambda > 0$, $\bar{M} \geq 1$ and every finite sequence $0 \leq t_1 \leq \dots \leq t_k \leq T$, $k \in \mathbb{N}$.

From this and (7) using ([1]; Lemma 2) it follows that the family $\{\hat{B}(t)\}$, $t \in [0, T]$, is double stable in \hat{X}_0^A , i.e.

$$\|(\mu - \hat{B}(t_k))^{-1}(\mu - \hat{B}(t_{k-1}))^{-1} \dots (\mu - \hat{B}(t_1))^{-1}\| \leq \frac{\bar{M}}{|\mu|^k}$$

and

$$\|(\mu - \hat{B}(t_1))^{-1}(\mu - \hat{B}(t_2))^{-1} \dots (\mu - \hat{B}(t_k))^{-1}\| \leq \frac{\bar{M}}{|\mu|^k}$$

for $\mu \neq 0$ and every finite sequence $0 \leq t_1 \leq \dots \leq t_k \leq T$.

From ([5], Lemmas 3.4 and 3.5) we obtain the stability of the family $\{\hat{\mathcal{A}}(t)\}$, $t \in [0, T]$. By assumption (Z_5) we deduce that the mapping

$$[0, T] \ni t \longrightarrow \hat{\mathcal{A}}(t) \begin{bmatrix} x \\ y \end{bmatrix} \in \hat{Y}^B \times \hat{X}_0^A$$

is of class C^1 . From this and stability of family $\{\hat{\mathcal{A}}(t)\}$, $t \in [0, T]$, we get existence of the fundamental solution $\mathcal{V}(t, s)$ for problem (11).

On the other hand, from (12), by inequalities

$$|x|_0^B \leq C\|x\|, \quad |x|_0^A \leq C_1\|x\|$$

for every $x \in X$ it follows that

$$\|f(t, x_1, y_1) - f(t, x_2, y_2)\| \leq L_1(\|x_1 - x_2\| + \|y_1 - y_2\|)$$

and

$$|f(t, x_1, y_1) - f(t, x_2, y_2)|_0^A \leq L_2(|x_1 - x_2|_0^B + |y_1 - y_2|_0^A).$$

To obtain the function \mathcal{U} we use the following iterative method

$$\begin{cases} \mathcal{U}'_1(t) = \hat{\mathcal{A}}(t)\mathcal{U}_1(t) + F(t, \mathcal{U}_0), \\ \mathcal{U}'_n(t) = \hat{\mathcal{A}}(t)\mathcal{U}_n(t) + F(t, \mathcal{U}_{n-1}(t)) \quad n \in \mathbb{N} \\ \mathcal{U}_n(0) = \mathcal{U}_0. \end{cases} \quad (13)$$

From this we get

$$\mathcal{U}_n \in C([0, T], \hat{Y}^B \times \hat{X}_0^A) \cap C^1((0, T], \hat{Y}^B \times \hat{X}_0^A), \quad n \in \mathbb{N}$$

and

$$\mathcal{U}_n(t) = \mathcal{V}(t, 0)\mathcal{U}_0 + \int_0^t \mathcal{V}(t, s)F(s, \mathcal{U}_{n-1}(s))ds, \quad t \in [0, T].$$

Since $Y \subset X$ is not dense in $(X, |\cdot|_0^B)$, we see that $\hat{Y}^B \subset X$. From this ([9], Th. 4.17) it follows that

$$\mathcal{U}(t) = \lim_{n \rightarrow \infty} \mathcal{U}_n(t) \quad (14)$$

is continuous in $[0, T]$, because $\mathcal{U}_n(t)$ converges uniformly in $[0, T]$.

We shall prove that $\mathcal{U} \in C^1((0, T], \hat{Y}^B \times \hat{X}_0^A)$. Indeed, let

$$\mathcal{U}_n(t) = \begin{bmatrix} u_n(t) \\ v_n(t) \end{bmatrix}, \quad \text{for } n \in \mathbb{N}, \quad t \in [0, T].$$

Hence by (13) we have for $t \in (0, T]$

$$u'_n(t) = v_n(t), \quad v'_n(t) = \hat{A}(t)u_n(t) + f(t, u_{n-1}(t), v_{n-1}(t)).$$

From this we get for $p, q \in \mathbb{N}$

$$\begin{aligned} |u'_p(t) - u'_q(t)|_0^B &= |v_p(t) - v_q(t)|_0^B, \\ |v'_p(t) - v'_q(t)|_0^A &\leq |\hat{A}(t)[u_p(t) - u_q(t)]|_0^A + |f(t, u_{p-1}(t), v_{p-1}(t)) - f(t, u_{q-1}(t), v_{q-1}(t))|_0^A. \end{aligned}$$

Thus,

$$\begin{aligned} |u'_p(t) - u'_q(t)|_0^B &\leq C \|v_p(t) - v_q(t)\|, \\ |v'_p(t) - v'_q(t)|_0^A &\leq \|\hat{A}^{-1}(0)\hat{A}(t)[u_p(t) - u_q(t)]\| + \\ &+ C_1 \|f(t, u_{p-1}(t), v_{p-1}(t)) - f(t, u_{q-1}(t), v_{q-1}(t))\| \leq \\ &\leq K \|u_p(t) - u_q(t)\| + C_1 L_1 (\|u_{p-1}(t) - u_{q-1}(t)\| + \|v_{p-1}(t) - v_{q-1}(t)\|). \end{aligned}$$

From (14) it follows that for $\varepsilon > 0$ there exists $n_0 \in N$ such that for $p, q > n_0$ we have

$$\sup\{|u'_p(t) - u'_q(t)|_0^B : t \in [\tau, T]\} < \varepsilon$$

and

$$\sup\{|v'_p(t) - v'_q(t)|_0^B : t \in [\tau, T]\} < \varepsilon$$

for every $\tau > 0$. This means that the mapping

$$(0, T] \ni t \longrightarrow \mathcal{U}(t) := \begin{bmatrix} u(t) \\ v(t) \end{bmatrix} \in \hat{Y}^B \times \hat{X}_0^A$$

is of class C^1 and is the unique classical solution of problem (11), where uniqueness is an immediate consequence of Gronwall's Lemma. \square

Theorem 2. *Under the assumptions of Theorem 1 the Cauchy problem (6) has a unique solution $u \in C^1([0, T], X) \cap C^2((0, T], \hat{X}_0^A)$, which is the unique solution of the integral equation*

$$u(t) = -\frac{\partial}{\partial s} S(t, s)|_{s=0} u_0 + S(t, 0) u_1 + \int_0^t S(t, s) f(s, u(s), u'(s)) ds, \quad (15)$$

where

$$S(t, s) := \Pi_1 \mathcal{V}(t, s) \begin{bmatrix} 0 \\ x \end{bmatrix} \quad \text{for each } x \in X_0^A,$$

and $\Pi_1 \begin{bmatrix} y \\ x \end{bmatrix} := y$ for $y \in \hat{Y}^B$, $x \in \hat{X}_0^A$ (cf. [11]).

Proof. The proof is the same as that of Theorem 7 in [11] and is omitted. \square

Definition 1. A function $u \in C^1([0, T], X)$ which is a solution of the integral equation (15) and $u(0) = u_0$, $u'(0) = u_1$ is called “a mild solution” of problem (1).

Corollary 1. *Under the assumptions of Theorem 1 problem (1) has a unique mild solution given by (15).*

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Institute of Mathematics, Cracow University of Technology
Warszawska 24, 31–155 Cracow, Poland
twiniars@usk.pk.edu.pl

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